



New Generation Robots MOTOMAN SDA, SIA Series



Certified for
ISO9001 and
ISO14001



JAB
QMS Accreditation
R009



JQA-0813



JQA-EM0924

New Generation of Robots to Enrich Our Futures

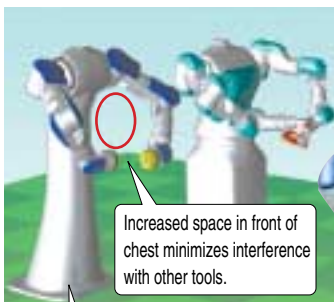
Dual-arm Robot

“Slim Body and Slim Arms” for easy installation in same space as human workers

The new dual-arm robot is designed to resemble the human figure.

The robot has slim arms that are similar to a human’s arms in size with seven joints in each arm. This human-size robot enables to replace the manual work to the automate operation without changing existing layout of the facility. The coordinated operation of seven axes for each arm and one at waist has made it possible to move efficiently with great dexterity requiring no further exclusive equipment for robots.

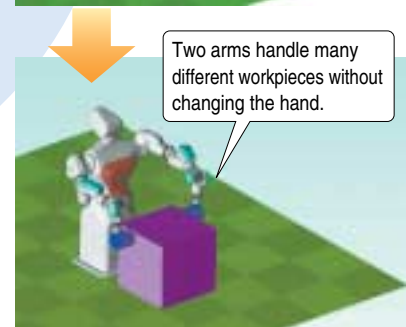
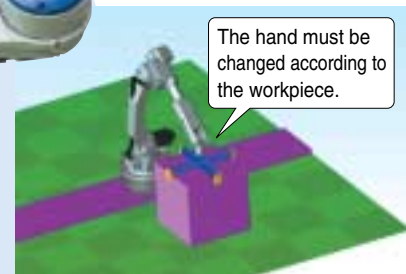
1. Human-like size and performance



Broadened range of applications with slim body and 7-axis arms

2. Versatility

- Holding of workpieces with both arms
- Positioning
- Freely transfer workpieces from one to another
- Independent control



3. Internal user I/O wiring harness and air lines

Besides eliminating peripheral interference, the SDA enabled complete offline simulation, too.



Product Line Dual-arm Robot



MOTOMAN-SDA5D/F
Payload: 5 kg/arm (10 kg/dual arms)



MOTOMAN-SDA10D/F
Payload: 10 kg/arm (20 kg/dual arms)



MOTOMAN-SDA20D/F
Payload: 20 kg/arm (40 kg/dual arms)

MOTOMAN leads the way in the new era and consistently offers new solutions to improve and to enhance the efficiency and quality of production lines. The MOTOMAN-SDA and -SIA series are new generation robots that will change the relationship between humans and robots as well as the concept of manufacturing with their unconventional robot forms (dual-arm and 7-axis single-arm) and the human-like movement. Now is the beginning of a new future that transcends our imaginations.

**7-axis
Single-arm
Robot**

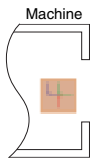
“Slim Arm” for high level of freedom in narrow spaces

The SIA single-arm robot resembles a human arm. With seven joints like a human arm, the SIA robot has a highly degree of freedom and it can bend, twist, or extend itself even in narrow spaces. This enables a space-saving, high-density layout.

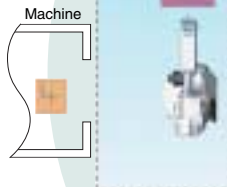
1. Space-saving and high-density layout

Installation in narrow spaces between machines is now possible. Optimal for high-density layouts.

7-axis robot requires less space than 6-axis robot.



Installation example of 7-axis robot



Installation example of 6-axis robot

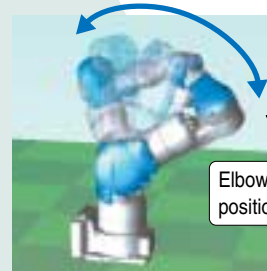
3. Internal user I/O wiring harness and air lines

Besides eliminating peripheral interference, the SIA enabled complete offline simulation, too.

2. Flexibility

- Elbow movement (unique and unprecedented feature in the industry)

The 7-axis configuration has enabled the angle of the elbow to be changed without affecting the tool position or posture.



Elbow moves with flange position unchanged.

- Flexible reach (to rear of workpiece)

The arm's flexibility enables the SIA robot to be installed in high-density layout without interference and to enter narrow spaces inaccessible to humans.

- Many installation options

The SIA robot can be installed in many ways without affecting functionality: on the floor, on the wall, on the ceiling, or on a slope.



Product Line 7-axis Single-arm Robot



MOTOMAN-SIA5D/F
Payload: 5 kg



MOTOMAN-SIA10D/F
Payload: 10 kg



MOTOMAN-SIA20D/F
Payload: 20 kg



MOTOMAN-SIA30D
Payload: 30 kg



MOTOMAN-SIA50D
Payload: 50 kg

New MOTOMAN Designs and Applications

Designed to Reduce Human Workload for Better Labor Conditions & Pursuit of Human-Robot Coexistence

Applications

Dual-arm Robot



Improvement on Logistic process

- Dual arms for secure handling
- Continuous handling without a temporary stand or a reverse jig
- Distributing parts for each process

Improvement on Assembling process

- Jigless assembly with dual arms
- Jigless positioning with dual arms
- High-accuracy assembly with high-speed, high-precision movements

Assembly of Automobile Engine



Sorting with Returnable Cases



Distributing of Parts



Assembly and Testing



Coordinated Operation with Welding Robot



Other Applications

- Assembly of LCD panels
- Assembly of electrical appliances/lighting
- Assembly of cable harnesses
- Handling, turning, and assembly of automotive parts
- Handling of lengthy automotive parts
- Transfer of beverage packs
- Transfer of returnable cases in containers

Technical Consulting

For more information on how to introduce the new generation robots into your system, contact your nearest Yaskawa representative.

7-axis Single-arm Robot



Improvement on Logistic process

- Installation in narrow spaces between machines
- Reach into narrow spaces
- Lifting operation (from a narrow space)

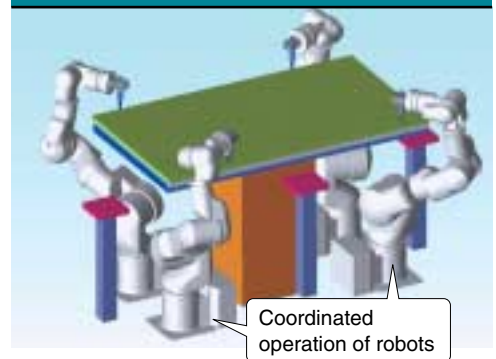
Improvement on Assembling process

- Assembly in high-density layout of robots
- Coordinated assembling operation of several robots without interference

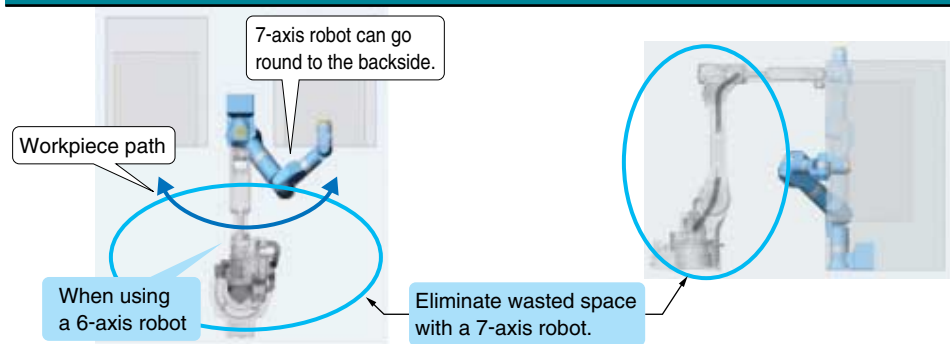
Attachment and Removal of Workpieces for NC Machines



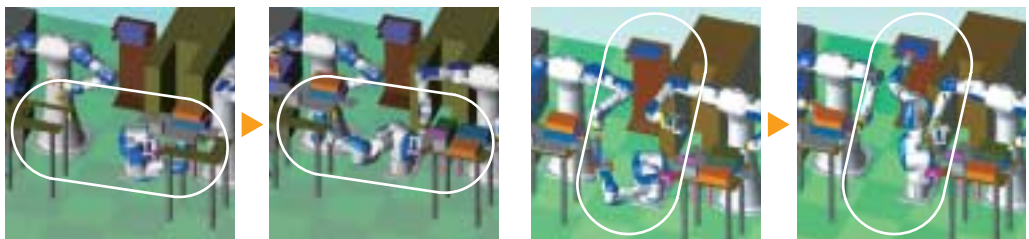
Assembly with 7-axis Robots in High-Density Layout



Handling between Machines in Limited Spaces



Transfer of Workpieces



Example 1: Transfer workpieces from right to left with only a single-arm robot

Example 2: Transfer workpieces from front to rear in minimal space

Technical Consulting

For more information on how to introduce the new generation robots into your system, contact your nearest Yaskawa representative.

Dual-arm Robot

MOTOMAN-SDA5D/F



Dual-arm 15 axes Payload: 5 kg/arm (10 kg/dual arms)

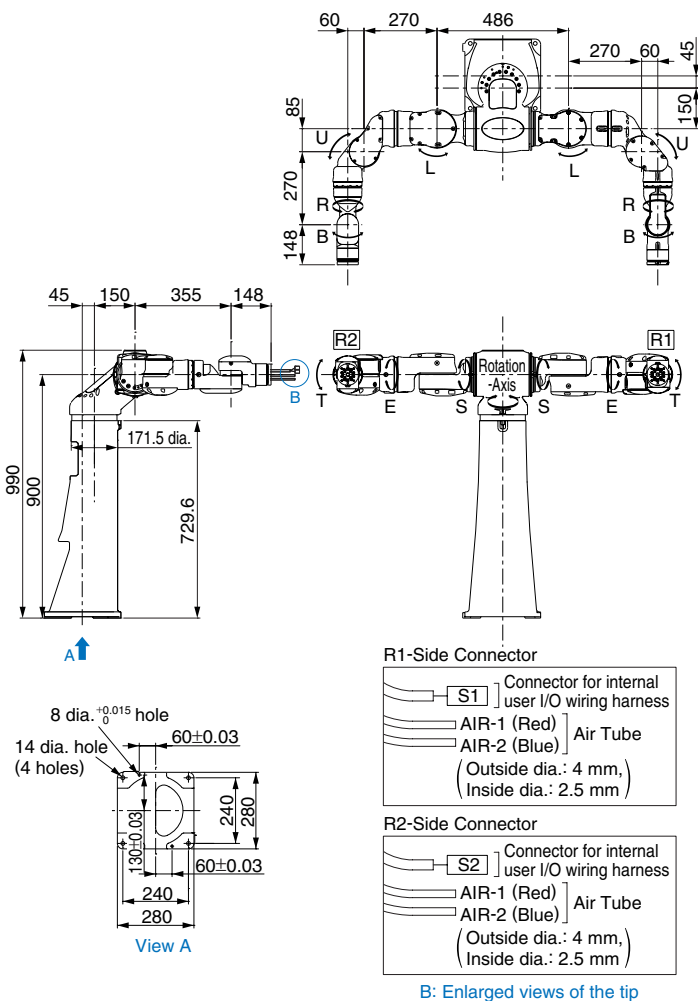
The MOTOMAN-SDA5D/F is a dual-arm robot with a 5 kg payload per arm (total load for dual-arm robot: 10 kg).

For small parts assembly and handling applications, this robot allows a more compact facility layout.

Features

- The arms have been slimmed by employing a newly developed miniaturized actuator for the wrist section, which comes closest to the parts and products. This has greatly reduced the interference of the arms with parts and products as well as interference between the two arms themselves.
- With a repetitive positioning accuracy of ± 0.06 mm, the robot is ideal for small parts assembly processes that require delicate work to be performed with high accuracy.
- The narrowing of the motion range that usually results when downsizing a robot is avoided by an ingenious mechanism used for the arm joints, so maximum range is maintained.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SDA5D/F*3	
Controlled Axis	15 (Articulated) [7 axes for left arm (R1), 7 axes for right arm (R2), 1 rotary axis]	
Payload	5 kg / arm	
Repeatability*1	± 0.06 mm	
Range of Motion	Rotation	$-170^\circ - +170^\circ$
	S-axis (lifting)	R1: $-90^\circ - +270^\circ$, R2: $-270^\circ - +90^\circ$
	L-axis (lower arm)	$-110^\circ - +110^\circ$
	E-axis (elbow twist)	$-170^\circ - +170^\circ$
	U-axis (upper arm)	$-90^\circ - +115^\circ$
	R-axis (upper arm twist)	$-180^\circ - +180^\circ$
	B-axis (wrist pitch/yaw)	$-110^\circ - +110^\circ$
Maximum Speed	T-axis (wrist twist)	$-180^\circ - +180^\circ$
	Rotation	3.14 rad/s, 180°/s
	S-axis (lifting)	3.49 rad/s, 200°/s
	L-axis (lower arm)	3.49 rad/s, 200°/s
	E-axis (elbow twist)	3.49 rad/s, 200°/s
	U-axis (upper arm)	3.49 rad/s, 200°/s
	R-axis (upper arm twist)	3.49 rad/s, 200°/s
Allowable Moment	B-axis (wrist pitch/yaw)	4.01 rad/s, 230°/s
	T-axis (wrist twist)	6.11 rad/s, 350°/s
	R-axis (upper arm twist)	14.7 N · m
Allowable Inertia (GD ² /4)	B-axis (wrist pitch/yaw)	14.7 N · m
	T-axis (wrist twist)	7.35 N · m
	R-axis (upper arm twist)	0.45 kg · m ²
Approx. Mass	110 kg	
Power Requirements*2	1.4 kVA	
Ambient Conditions	Temperature	0°C to +40°C
	Humidity	20 to 80%RH (non-condensing)
	Vibration	Less than 4.9 m/s ²
Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma) 	

*1 : Conforms to JIS B 8432.

*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

MOTOMAN-SDA10D/F



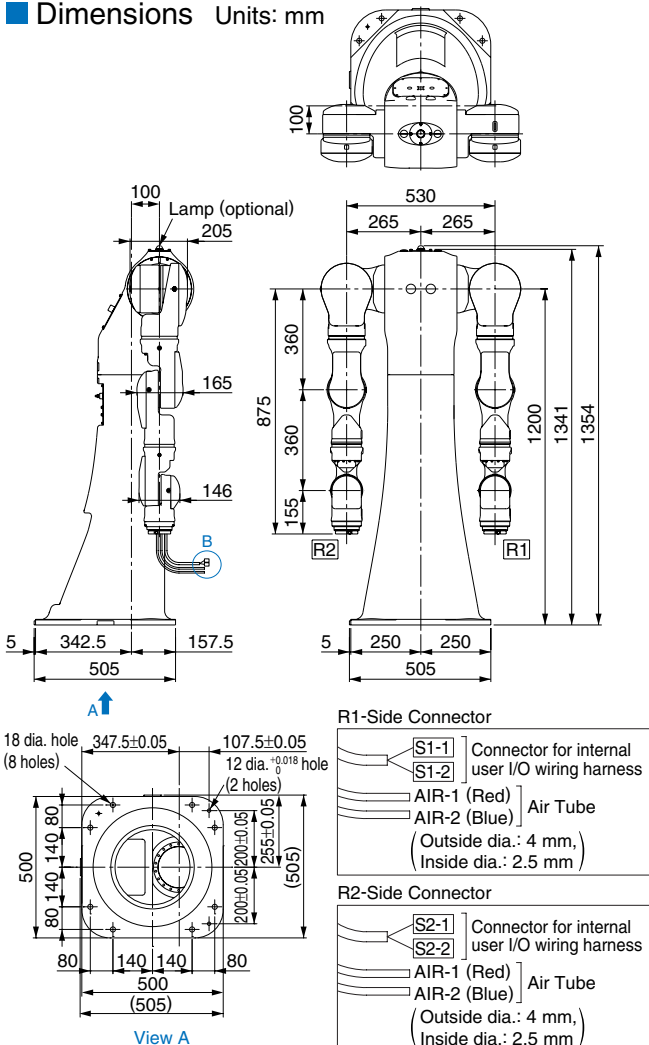
Dual-arm (15 axes) **Payload: 10 kg/arm (20 kg/dual arms)**

The MOTOMAN-SDA10D/F is human-sized and has two 7-axis arms that enable human-like movements. Capable of assembling and handling heavy objects up to 10 kg per arm (total load for dual-arm robot: 20 kg). Easily applicable to existing manufacturing lines because of its human-like size.

Features

- Same level of capability as a human in assembling and handling heavy objects.
- Human-like flexibility of motions achieved by having two arms with 7 axes each and a rotary axis at the waist.
- High-precision movement for accuracy.
- Enhanced acceleration performance for reduced operating time.
- Independent control and operation of two arms for higher efficiency.
- Keep costs low as the two arms can transfer workpieces from arm to arm and turn them without using a temporary stand or a reverse jig.

■ Dimensions Units: mm



■ Manipulator Specifications

Model	MOTOMAN-SDA10D/F*3		
Controlled Axis	15 (Articulated) [7 axes for left arm (R1), 7 axes for right arm (R2), 1 rotary axis]		
Payload	10 kg / arm		
Repeatability*1	±0.1 mm		
Range of Motion	R1	Rotation	-170° ~ +170°
		S-axis (lifting)	-180° ~ +180°
	R2	L-axis (lower arm)	-110° ~ +110°
		E-axis (elbow twist)	-170° ~ +170°
		U-axis (upper arm)	-135° ~ +135°
		R-axis (upper arm twist)	-180° ~ +180°
		B-axis (wrist pitch/yaw)	-110° ~ +110°
T-axis (wrist twist)	-180° ~ +180°		
Maximum Speed	R1	Rotation	2.27 rad/s, 130°/s
		S-axis (lifting)	2.97 rad/s, 170°/s
	R2	L-axis (lower arm)	2.97 rad/s, 170°/s
		E-axis (elbow twist)	2.97 rad/s, 170°/s
		U-axis (upper arm)	2.97 rad/s, 170°/s
		R-axis (upper arm twist)	3.49 rad/s, 200°/s
		B-axis (wrist pitch/yaw)	3.49 rad/s, 200°/s
T-axis (wrist twist)	6.98 rad/s, 400°/s		
Allowable Moment	R-axis (upper arm twist)	31.4 N · m	
	B-axis (wrist pitch/yaw)	31.4 N · m	
	T-axis (wrist twist)	19.6 N · m	
Allowable Inertia (GD ² /4)	R-axis (upper arm twist)	1.0 kg · m ²	
	B-axis (wrist pitch/yaw)	1.0 kg · m ²	
T-axis (wrist twist)	0.4 kg · m ²		
Approx. Mass	220 kg		
Power Requirements*2	2.7 kVA		
Ambient Conditions	Temperature	0°C to +40°C	
	Humidity	20 to 80%RH (non-condensing)	
	Vibration	Less than 4.9 m/s ²	
Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma) 		

*1 : Conforms to JIS B 8432.

*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

Dual-arm Robot

MOTOMAN-SDA20D/F



Dual-arm 15 axes Payload: 20 kg/arm (40 kg/dual arms)

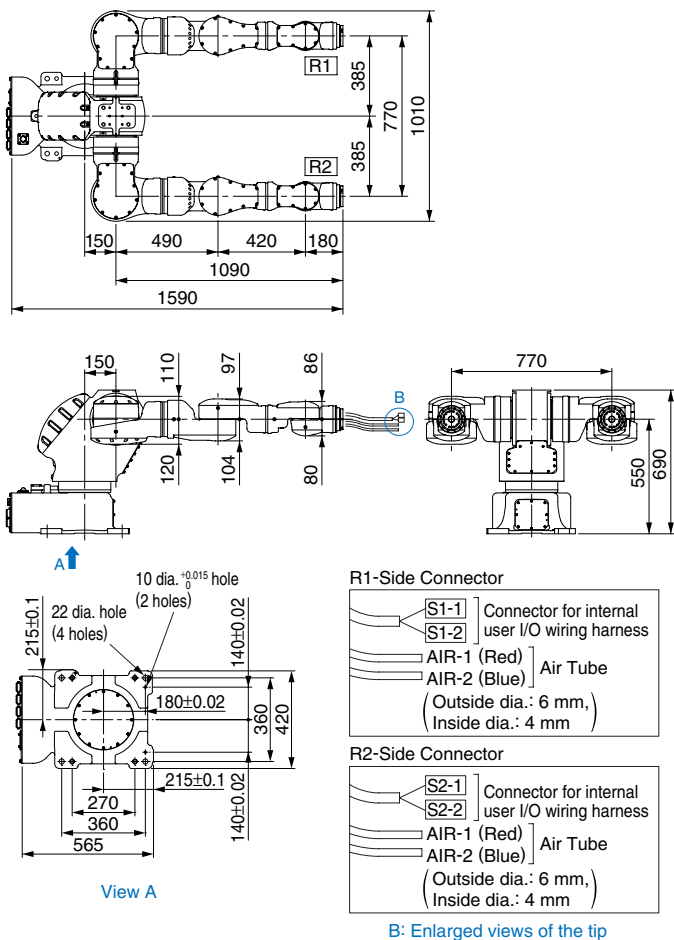
The MOTOMAN-SDA20D/F is a high-payload robot that is capable of handling heavy objects up to 20 kg per arm (total load for dual-arm robot: 40 kg).

Same as the SDA10D/F, the SDA20D/F has 15 axes and realizes human-like flexibility of movement.

Features

- Handling of heavy objects up to 20 kg per arm (total load for dual-arm robot: 40 kg).
- High-speed and high-precision operation.
- Human-like flexibility of motions achieved by having two arms with 7 axes each and a rotary axis at the waist.
- The design of the hands can be simplified even for holding large objects, because the two arms actually hold and carry the objects.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SDA20D/F*3		
Controlled Axis	15 (Articulated) [7 axes for left arm (R1), 7 axes for right arm (R2), 1 rotary axis]		
Payload	20 kg / arm		
Repeatability*1	±0.1 mm		
Range of Motion	R1	Rotation	-180° - +180°
		S-axis (lifting)	-180° - +180°
	R2	L-axis (lower arm)	-110° - +110°
		E-axis (elbow twist)	-170° - +170°
		U-axis (upper arm)	-130° - +130°
		R-axis (upper arm twist)	-180° - +180°
		B-axis (wrist pitch/yaw)	-110° - +110°
		T-axis (wrist twist)	-180° - +180°
Maximum Speed	R1	Rotation	2.18 rad/s, 125°/s
		S-axis (lifting)	2.27 rad/s, 130°/s
	R2	L-axis (lower arm)	2.27 rad/s, 130°/s
		E-axis (elbow twist)	2.97 rad/s, 170°/s
		U-axis (upper arm)	2.97 rad/s, 170°/s
		R-axis (upper arm twist)	3.49 rad/s, 200°/s
		B-axis (wrist pitch/yaw)	3.49 rad/s, 200°/s
		T-axis (wrist twist)	6.98 rad/s, 400°/s
Allowable Moment	R-axis (upper arm twist)	58.8 N · m	
	B-axis (wrist pitch/yaw)	58.8 N · m	
	T-axis (wrist twist)	29.4 N · m	
Allowable Inertia (GD ² /4)	R-axis (upper arm twist)	4.0 kg · m ²	
	B-axis (wrist pitch/yaw)	4.0 kg · m ²	
	T-axis (wrist twist)	2.0 kg · m ²	
Approx. Mass	380 kg		
Power Requirements*2	4.4 kVA		
Ambient Conditions	Temperature	0°C to +40°C	
	Humidity	20 to 80%RH (non-condensing)	
	Vibration	Less than 4.9 m/s ²	
Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma) 		

*1 : Conforms to JIS B 8432.

*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

7-axis Single-arm Robot

MOTOMAN-SIA5D/F

Single-arm 7 axes Payload: 5 kg



The MOTOMAN-SIA5D/F features seven controlled axes with a 5 kg payload. Ideal for handling small objects in applications that require the robot to be installed in limited space, and where a high level of positioning accuracy is needed.

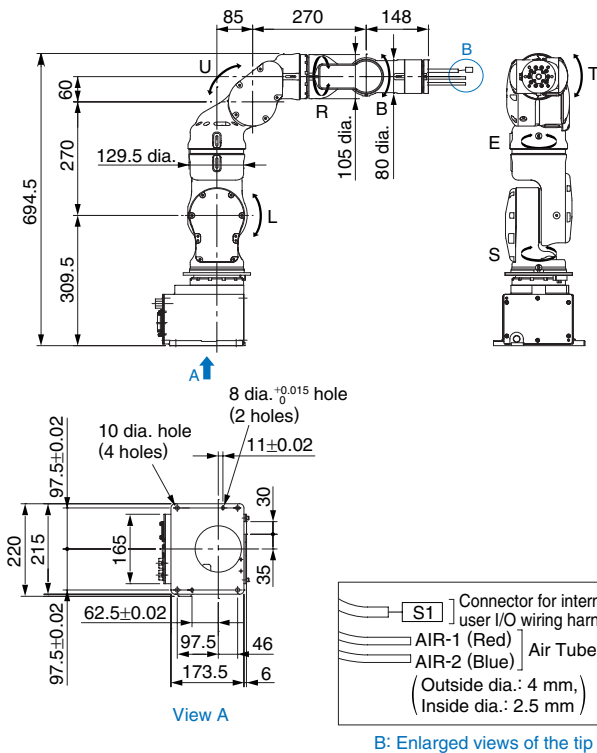
Features

- High degree of motion like a human arm with its 7-axis arm.
- The arm has been slimmed by employing a newly developed miniaturized actuator for the wrist section, greatly reducing the interference of the arm with the workpiece.
- The narrowing of the motion range that usually results when downsizing a robot is avoided by an ingenious mechanism used for the arm joints, so maximum range is maintained.
- Light and weighs only 30 kg, so many installation choices are available: floor, ceiling, or wall.
- Environmental resistance: models with drip-proofing and for clean-room use are available.
 - Drip-proof protection level: IP65 for arm and IP54 for base. (Not acceptable to SIA5D/F flange at tip. A different model with a waterproof flange is available.)
 - Cleanliness level: ISO class 5 and complies with ISO 14644 standards when downflow of robot environment is 0.4 m/s or faster.

Notes : 1. Conduct a warming-up operation when the robot is to be used at low temperatures (10 degrees Celsius or lower).
2. Contact Yaskawa Electric for details.

- By utilizing internal user I/O wiring harness and air lines integrated in the arm, layout can be planned offline without worrying about peripheral interference. (Internal user I/O wiring harness and air lines specifications: two air lines and eight-core cables)
Note : External axis specification for a hand can be accommodated. Contact Yaskawa Electric regarding your requirements.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SIA5D/F*3	
Controlled Axis	7 (Vertically articulated)	
Payload	5 kg	
Repeatability*1	±0.06 mm	
Range of Motion	S-axis (turning)	-180° - +180°
	L-axis (lower arm)	-110° - +110°
	E-axis (elbow twist)	-170° - +170°
	U-axis (upper arm)	-90° - +155°
	R-axis (wrist roll)	-180° - +180°
	B-axis (wrist pitch/yaw)	-110° - +110°
	T-axis (wrist twist)	-180° - +180°
Maximum Speed	S-axis (turning)	3.49 rad/s, 200°/s
	L-axis (lower arm)	3.49 rad/s, 200°/s
	E-axis (elbow twist)	3.49 rad/s, 200°/s
	U-axis (upper arm)	3.49 rad/s, 200°/s
	R-axis (wrist roll)	3.49 rad/s, 200°/s
	B-axis (wrist pitch/yaw)	4.01 rad/s, 230°/s
	T-axis (wrist twist)	6.11 rad/s, 350°/s
Allowable Moment	R-axis (wrist roll)	14.7 N · m
	B-axis (wrist pitch/yaw)	14.7 N · m
	T-axis (wrist twist)	7.35 N · m
Allowable Inertia (GD ² /4)	R-axis (wrist roll)	0.45 kg · m ²
	B-axis (wrist pitch/yaw)	0.45 kg · m ²
	T-axis (wrist twist)	0.11 kg · m ²
Approx. Mass	30 kg	
Power Requirements*2	1.0 kVA	
Ambient Conditions	Temperature	0°C to +40°C
	Humidity	20 to 80%RH (non-condensing)
	Vibration	Less than 4.9 m/s ²
	Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma)

*1 : Conforms to JIS B 8432.

*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

7-axis Single-arm Robot

MOTOMAN-SIA10D/F

Single-arm

7 axes

Payload: 10 kg



The MOTOMAN-SIA10D/F is a 7-axis robot with a 10 kg payload and is more compact than the SIA20D/F.

Optimal for handling small objects in limited space.

Features

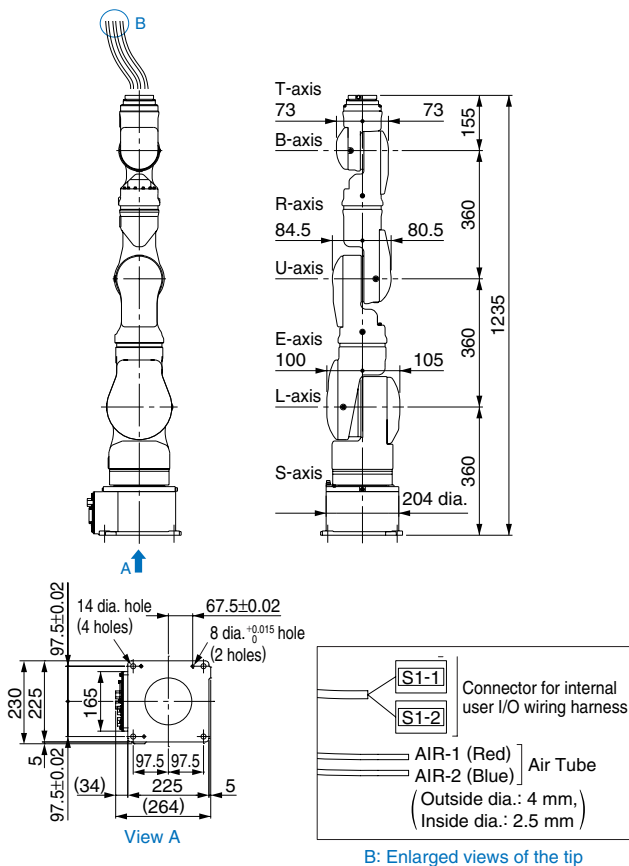
- High degree of motion like a human arm with its 7-axis arm.
- The high flexibility of motion makes operation possible even in narrow spaces inaccessible to humans.
- Folds to compact size when not in use.
- Many installation options: on the floor, on the wall or on the ceiling.
- Optimal for handling small objects.
- Environmental resistance: models with drip-proofing and for clean-room use are available.
 - Drip-proof protection level: IP65 for arm and IP54 for base. (Not acceptable to SIA10D/F flange at tip. A different model with a waterproof flange is available.)
 - Cleanliness level: ISO class 5 and complies with ISO 14644 standards when downflow of robot environment is 0.4 m/s or faster.

Notes : 1. Conduct a warming-up operation when the robot is to be used at low temperatures (10 degrees Celsius or lower).
2. Contact Yaskawa Electric for details.

- By utilizing internal user I/O wiring harness and air lines integrated in the arm, layout can be planned offline without worrying about peripheral interference. (Internal user I/O wiring harness and air lines specifications: two air hoses and twelve-core cables)

Note : External axis specification for a hand can be accommodated. Contact Yaskawa Electric regarding your requirements.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SIA10D/F*3	
Controlled Axis	7 (Vertically articulated)	
Payload	10 kg	
Repeatability*1	±0.1 mm	
Range of Motion	S-axis (turning)	-180° - +180°
	L-axis (lower arm)	-110° - +110°
	E-axis (elbow twist)	-170° - +170°
	U-axis (upper arm)	-135° - +135°
	R-axis (wrist roll)	-180° - +180°
	B-axis (wrist pitch/yaw)	-110° - +110°
	T-axis (wrist twist)	-180° - +180°
Maximum Speed	S-axis (turning)	2.97 rad/s, 170°/s
	L-axis (lower arm)	2.97 rad/s, 170°/s
	E-axis (elbow twist)	2.97 rad/s, 170°/s
	U-axis (upper arm)	2.97 rad/s, 170°/s
	R-axis (wrist roll)	3.49 rad/s, 200°/s
	B-axis (wrist pitch/yaw)	3.49 rad/s, 200°/s
	T-axis (wrist twist)	6.98 rad/s, 400°/s
Allowable Moment	R-axis (wrist roll)	31.4 N · m
	B-axis (wrist pitch/yaw)	31.4 N · m
	T-axis (wrist twist)	19.6 N · m
Allowable Inertia (GD ² /4)	R-axis (wrist roll)	1.0 kg · m ²
	B-axis (wrist pitch/yaw)	1.0 kg · m ²
	T-axis (wrist twist)	0.4 kg · m ²
Approx. Mass	60 kg	
Power Requirements*2	1.5 kVA	
Ambient Conditions	Temperature	0°C to +40°C
	Humidity	20 to 80%RH (non-condensing)
	Vibration	Less than 4.9 m/s ²
	Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma)

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*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

MOTOMAN-SIA20D/F

Single-arm

7 axes

Payload: 20 kg



With its unique arm form and 7 degrees of freedom, the MOTOMAN-SIA20D/F has achieved flexibility of movement that was impossible for robots till now.

Features

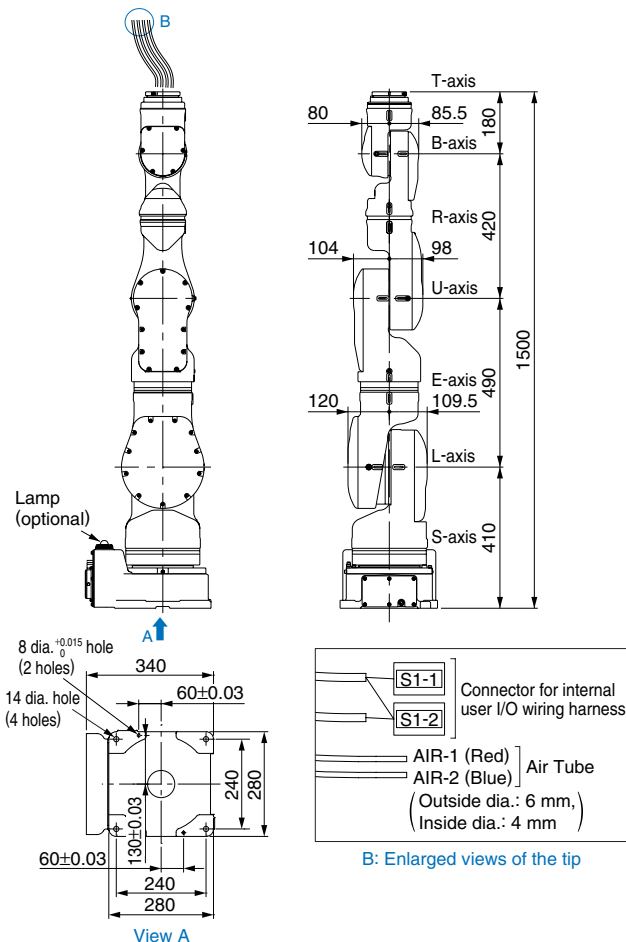
- High degree of motion like a human arm with its 7-axis arm.
- The high flexibility of motion makes operation possible even in narrow spaces inaccessible to humans.
- Folds to compact size when not in use.
- Many installation options: on the floor, on the wall or on the ceiling.
- Assembles and handles heavy objects up to 20 kg.
- Environmental resistance: models with drip-proofing and for clean-room use are available.
 - Drip-proof protection level: IP65 for arm and IP54 for base.(Not acceptable to SIA20D/F flange at tip. A different model with a waterproof flange is available.)
 - Cleanness level: ISO class 5 and complies with ISO 14644 standards when downflow of robot environment is 0.4 m/s or faster.

Notes : 1. Conduct a warming-up operation when the robot is to be used at low temperatures (10 degrees Celsius or lower).
2. Contact Yaskawa Electric for details.

- By utilizing internal user I/O wiring harness and air lines integrated in the arm, layout can be planned offline without worrying about peripheral interference.
(Internal user I/O wiring harness and air lines specifications: two air hoses and sixteen-core cables)

Note : External axis specification for a hand can be accommodated. Contact Yaskawa Electric regarding your requirements.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SIA20D/F*3	
Controlled Axis	7 (Vertically articulated)	
Payload	20 kg	
Repeatability*1	±0.1 mm	
Range of Motion	S-axis (turning)	-180° - +180°
	L-axis (lower arm)	-110° - +110°
	E-axis (elbow twist)	-170° - +170°
	U-axis (upper arm)	-130° - +130°
	R-axis (wrist roll)	-180° - +180°
	B-axis (wrist pitch/yaw)	-110° - +110°
	T-axis (wrist twist)	-180° - +180°
Maximum Speed	S-axis (turning)	2.27 rad/s, 130°/s
	L-axis (lower arm)	2.27 rad/s, 130°/s
	E-axis (elbow twist)	2.97 rad/s, 170°/s
	U-axis (upper arm)	2.97 rad/s, 170°/s
	R-axis (wrist roll)	3.49 rad/s, 200°/s
	B-axis (wrist pitch/yaw)	3.49 rad/s, 200°/s
	T-axis (wrist twist)	6.98 rad/s, 400°/s
Allowable Moment	R-axis (wrist roll)	58.8 N · m
	B-axis (wrist pitch/yaw)	58.8 N · m
	T-axis (wrist twist)	29.4 N · m
Allowable Inertia (GD ² /4)	R-axis (wrist roll)	4.0 kg · m ²
	B-axis (wrist pitch/yaw)	4.0 kg · m ²
	T-axis (wrist twist)	2.0 kg · m ²
Approx. Mass	120 kg	
Power Requirements*2	2.2 kVA	
Ambient Conditions	Temperature	0°C to +40°C
	Humidity	20 to 80%RH (non-condensing)
	Vibration	Less than 4.9 m/s ²
	Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma)

*1 : Conforms to JIS B 8432.

*2 : Varies in accordance with applications and motion patterns.

*3 : The letter "F" at the end of the model number indicates that an FS100 controller is used to control the robot. When a DX100 controller is used, the model number will have the letter "D" at the end.

Note : SI units are used for specifications.

7-axis Single-arm Robot

MOTOMAN-SIA30D

Single-arm

7 axes

Payload: 30 kg

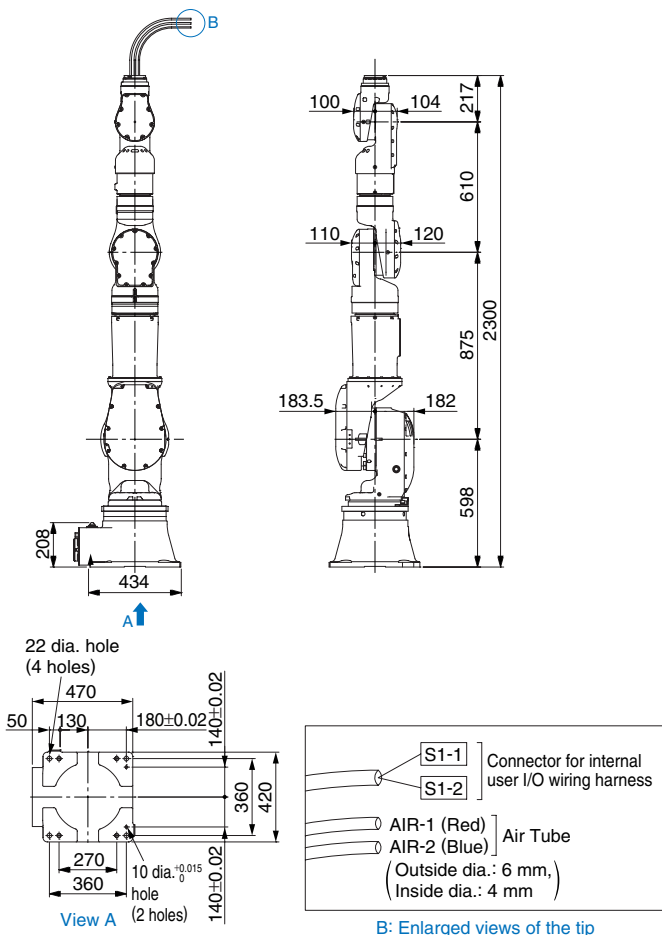


The MOTOMAN-SIA30D features seven controlled axes with a 30 kg payload. The wide range of motion and flexible movement expand the possible range of applications.

Features

- High degree of motion like a human arm with its 7-axis arm.
 - High-speed and high-precision operation.
 - Folds to compact size when not in use.
 - Assembles and handles heavy objects up to 30 kg.
 - Many installation options: on the floor, on the wall or on the ceiling.
 - Environmental resistance: model with drip-proofing is available. Protection level: IP65 for arm and IP54 for base. (Not acceptable to SIA30D flange at tip. A different model with a waterproof flange is available.)
- Notes : 1. Conduct a warming-up operation when the robot is to be used at low temperatures (10 degrees Celsius or lower).
2. Contact Yaskawa Electric for details.
- By utilizing internal user I/O wiring harness and air lines integrated in the arm, layout can be planned offline without worrying about peripheral interference. (Internal user I/O wiring harness and air lines specifications: two air hoses and eight-core cables)
- Note : External axis specification for a hand can be accommodated. Contact Yaskawa Electric regarding your requirements.

Dimensions Units: mm



Manipulator Specifications

Model	MOTOMAN-SIA30D	
Controlled Axis	7 (Vertically articulated)	
Payload	30 kg	
Repeatability*1	±0.1 mm	
Range of Motion	S-axis (turning)	-180° - +180°
	L-axis (lower arm)	-125° - +125°
	E-axis (elbow twist)	-170° - +170°
	U-axis (upper arm)	-110° - +110°
	R-axis (wrist roll)	-170° - +170°
	B-axis (wrist pitch/yaw)	-110° - +110°
	T-axis (wrist twist)	-180° - +180°
Maximum Speed	S-axis (turning)	2.27 rad/s, 130°/s
	L-axis (lower arm)	2.27 rad/s, 130°/s
	E-axis (elbow twist)	2.27 rad/s, 130°/s
	U-axis (upper arm)	2.27 rad/s, 130°/s
	R-axis (wrist roll)	2.97 rad/s, 170°/s
	B-axis (wrist pitch/yaw)	2.97 rad/s, 170°/s
Allowable Moment	R-axis (wrist roll)	117.6 N · m
	B-axis (wrist pitch/yaw)	117.6 N · m
	T-axis (wrist twist)	58.8 N · m
Allowable Inertia (GD ² /4)	R-axis (wrist roll)	6.0 kg · m ²
	B-axis (wrist pitch/yaw)	6.0 kg · m ²
	T-axis (wrist twist)	3.0 kg · m ²
Approx. Mass	345 kg	
Power Requirements*2	Temperature	0°C to +40°C
	Humidity	20 to 80%RH (non-condensing)
	Vibration	Less than 4.9 m/s ²
Ambient Conditions	Others	<ul style="list-style-type: none"> • Free from corrosive or explosive gasses and liquids • Free from exposure to water, oil or dust • Free from excessive electrical noise (plasma)

*1 : Conforms to JIS B 8432.
*2 : Varies in accordance with applications and motion patterns.
Note : SI units are used for specifications.

SDA, SIA Series

Controller Specifications

Items	DX100 Controller	FS100 Controller
Configuration	Dust proof	Standard : IP20 (open structure) Option : IP54 (dustproof housing)
Dimensions (W)×(D)×(H), Mass	MOTOMAN-SDA5D, SDA10D, SDA20D : 500×580×880 mm, 150 kg max.(Possible to control 1 external axis.)	MOTOMAN-SDA5F, SDA10F, SDA20F : 470×475×420 mm (includes projecting parts.) 40 kg, (Possible to control 1 external axis.)
	MOTOMAN-SIA5D, SIA10D, SIA20D : 500×580×580 mm, 100 kg max.(Possible to control 1 external axis.)	MOTOMAN-SIA5F, SIA10F, SIA20F : 470×475×210 mm (includes projecting parts.) 20 kg, (Possible to control 1 external axis.)
	MOTOMAN-SIA30D, SIA50D : 425×450×1200 mm, 100 kg max.(Possible to control 2 external axes.)	
Cooling System	Indirect cooling	Direct cooling
Ambient Temperature	During operation : 0°C to +45°C During storage : -10°C to +60°C	During operation : 0°C to +40°C During storage : -10°C to +60°C
Relative Humidity	90% max. (non-condensing)	90% max. (non-condensing)
Power Supply	Three-phase 200/220 VAC (+10% to -15%), 60 Hz (±2%)(Japan) Three-phase 200 VAC (+10% to -15%), 50 Hz (±2%)(Japan)	Three-phase 200/220 VAC (+10%, -15%), 50/60 Hz Single-phase 200/230 VAC (+10%, -15%), 50/60 Hz
Grounding	Grounding resistance : 100 Ω or less	Grounding resistance : 100 Ω or less
Digital I/Os	Specialized signals : 23 inputs and 5 outputs General signals : 40 inputs and 40 outputs Max. I/O (optional) : 2,048 inputs and 2,048 outputs	Specialized signals : 19 inputs and 2 outputs General signals : 28 inputs and 28 outputs Max. I/O (optional) : 1,024 inputs and 1,024 outputs
Positioning System	By serial encoder	By serial encoder
Programming Capacity	JOB : 200,000 steps, 10,000 instructions CIO ladder : 20,000 steps	JOB : 10,000 steps, 1,000 instructions CIO ladder : 1,500 steps
Expansion Slots	PCI : 2 slots for main CPUs and 1 slot for servo CPU 1 additional slot for sensor board	MP2000 bus×5 slots
LAN (Connection to Host)	1(10BASE-T/100BASE-TX)	1(10BASE-T/100BASE-TX)
Interface	RS-232C : 1ch	RS-232C : 1ch
Control Method	Software servo control	Software servo control
Drive Units	Standard 6 axes and 2 additional single-axis amplifiers can be mounted (8 axes max.)	Standard 6 axes and 1 additional single-axis amplifiers can be mounted.
Painting Color	Munsell notation 5Y7/1 (reference value)	Munsell notation 5Y7/1 (reference value)
Items	Programming Pendant *	
Dimensions	169(W) × 314.5(H) × 50(D) mm	
Mass	0.990 kg	
Material	Reinforced plastics	
Operation Device	Select keys, axis keys(8 axes),numerical/application keys, Mode switch with key (mode : teach, play, and remote), emergency stop button, enable switch, compact flash card interface device (compact flash is optional.),USB port (1 port)	
Display	640 × 480 pixels color LCD, touch panel (Alphanumeric characters, Chinese characters, Japanese letters, Others)	
IEC Protection Class	IP65	
Cable Length	Standard : 8 m, Max. : 36 m (optional)	Standard : 8 m, optional : 20 m max.

*: The programming pendant for the FS100 controller is optional. The model number of the programming pendant differs from that of the programming pendant for the DX100 controller.

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YASKAWA ELECTRIC CORPORATION

In the event that the end user of this product is to be the military and said product is to be employed in any weapons systems or the manufacture thereof, the export will fall under the relevant regulations as stipulated in the Foreign Exchange and Foreign Trade Regulations. Therefore, be sure to follow all procedures and submit all relevant documentation according to any and all rules, regulations and laws that may apply.

Specifications are subject to change without notice for ongoing product modifications and improvements.

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